

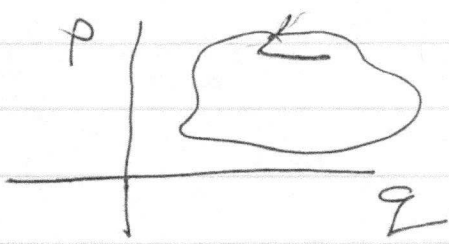
Action - Angle Variables

→ Extending the Concepts
of Adiabatic Invariance.

Action-Angle Variables

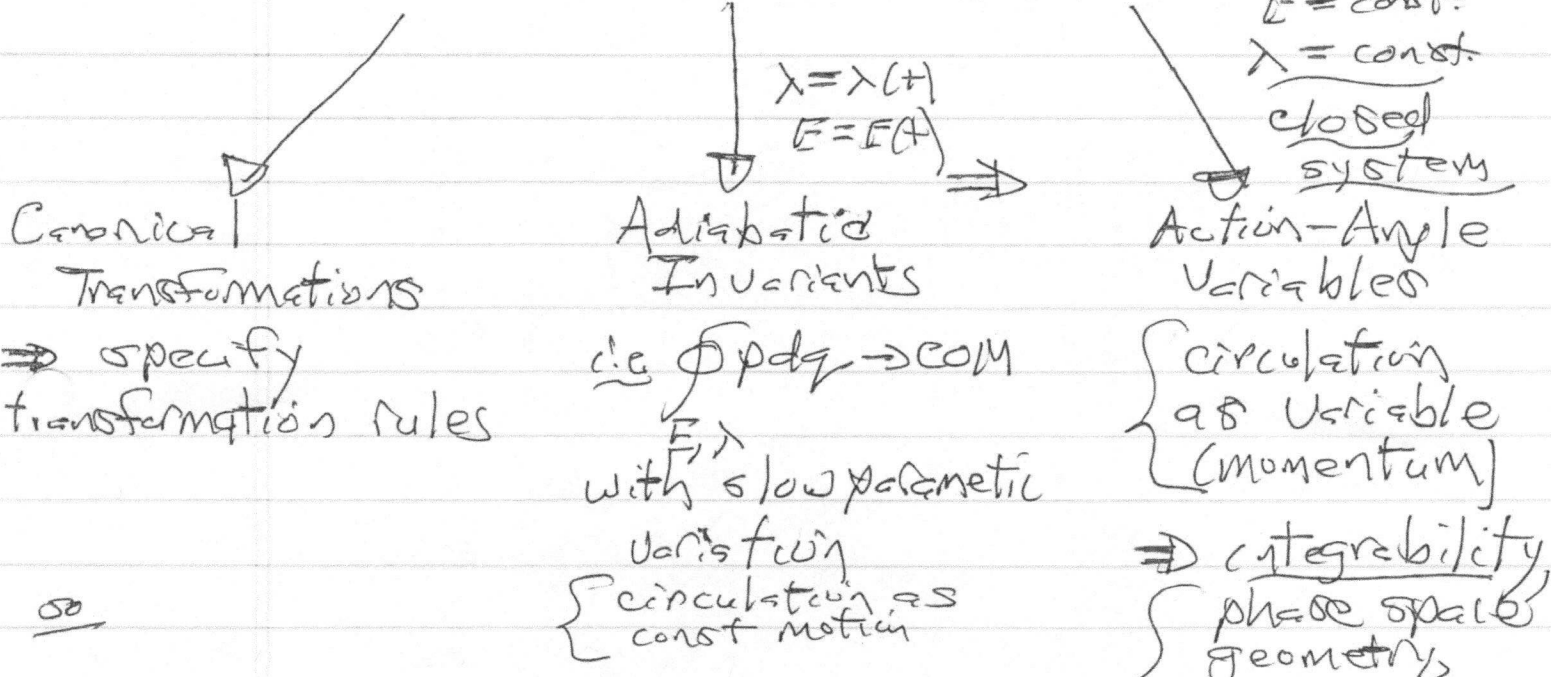
($L/L \rightarrow$ canonical variables)

Key concept: $\oint p dq$



Phase Space Circulation

\Leftrightarrow Poincaré - Cartan Invariant



Canonical Transformations
 \Rightarrow specify transformation rules

Adiabatic Invariants
 $\lambda = \lambda(t)$
 $E = E(t)$
 i.e. $\oint p dq \rightarrow \text{COM}$
 E, λ
 with slow parametric variation
 $\left\{ \begin{array}{l} \text{circulation as} \\ \text{const motion} \end{array} \right.$

$E = \text{const.}$
 $\lambda = \text{const.}$
 closed system
 Action-Angle Variables
 $\left\{ \begin{array}{l} \text{circulation as variable} \\ \text{(momentum)} \end{array} \right.$
 \Rightarrow integrability
 $\left\{ \begin{array}{l} \text{phase space geometry} \\ \text{resonance} \end{array} \right.$

Action-Angle variables

\rightarrow seek variables (i.e. C.T. : $p, q \rightarrow I, \theta$)
 off:

$H = H(I)$, so $\dot{I} = 0$ integrable
 $\dot{\theta} = \frac{\partial H}{\partial I}$

i.e. C.T. to conserved momentum, cyclic coordinate $\theta = \omega t + \theta_0$

\Rightarrow C.T. is equivalent to integration of system. $\left\{ \begin{array}{l} \text{A/A are variables} \\ \text{on which system} \\ \text{integrated} \end{array} \right.$

→ crudely: integrate via new variables
 s/t $I \rightarrow$ 'generalized radius'
 $Q \rightarrow$ " " angle

so

$$p, z \rightarrow Q, I$$

$$H(p, z) \rightarrow H'(I) \quad \begin{array}{l} \dot{I} = 0 \\ \dot{Q} = \omega \end{array}$$

C-T. : independent variables q, I
 (z, p)

$$\Rightarrow \text{Type II: } F_2 = F_2(q, I)$$

$$\underline{\text{so}} \quad p = \frac{\partial F_2}{\partial z}, \quad Q = \frac{\partial F_2}{\partial I}$$

$$\Rightarrow p = \frac{\partial F_2}{\partial z}, \quad \blacksquare \quad Q = \frac{\partial F_2}{\partial I}$$

but $p = \frac{\partial F_2}{\partial z}$ equiv. to $p = \frac{\partial S}{\partial z}$

from H-J theory

(always, for Type II)

so can write in terms action as
 generating function, i.e.

$$F_2(q, I) = F_2(z, I) = S(z, I).$$

$$\omega \quad \theta = \frac{\partial S_0}{\partial I}, \quad p = \frac{\partial S_0}{\partial z}$$

Now, further:

$S_0 = S_0(z, I)$ indep. time; i.e. $\lambda = \lambda(t) = \text{const.}$

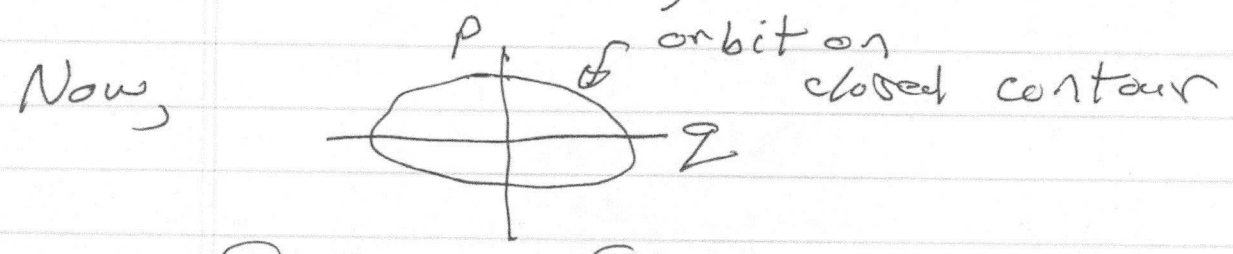
and ~~scribble~~ $H(z, p) \rightarrow H(I)$, with θ cyclic
 in new variables \rightarrow EOM: $= E(I)$ cyclic

$$\Rightarrow \dot{I} = -\frac{\partial H}{\partial \theta} = 0, \quad \dot{\theta} = \frac{\partial H}{\partial I} = \omega(I)$$

angular frequency

i.e. I and E constant.

contrast: Adiabatic invariants \Rightarrow
 $I \sim \text{const}$, E evolves as ω evolves



$$I = \oint p dz = \int dp dz$$

\downarrow $\frac{1}{2\pi}$ \downarrow
 1 circuit phase volume
 circulation

another way:

$$S_0 = S_0(q, I) \quad , \quad \rho = \frac{\partial S_0}{\partial q}$$

$$\theta = \frac{\partial S_0}{\partial I}$$

oo

$$\frac{d\theta}{dq} = \frac{\partial}{\partial q} \frac{\partial S}{\partial I} = \frac{\partial}{\partial I} \frac{\partial S}{\partial q}$$

$$d\theta = \frac{\partial}{\partial I} \frac{\partial S}{\partial q} dq$$

⇒

$$2\pi = \frac{\partial}{\partial I} \oint \frac{\partial S}{\partial q} dq$$

$$= \frac{\partial}{\partial I} \oint \rho dq$$

$$\Rightarrow \boxed{I = \oint \frac{\rho}{2\pi} dq \quad \rightarrow \text{Action Variable}}$$

$$\boxed{\dot{\theta} = \frac{\partial H}{\partial I} = \frac{\partial E(I)}{\partial I} \equiv \omega(I) \quad \text{angle variable.}}$$

I → radius

ω → winding rate, frequency

Comparison / Contrast

Adiabatic Invariants

$$\lambda = \lambda(H), \text{ open loop}$$

$$I = \oint_{E, \lambda} p dq \sim \begin{cases} \text{approx} \\ \text{COM} \end{cases}$$

E varied with ω ,
 $I \sim \text{const.}$

COM for multiple
scale problems

1 adiabatic ch.v. per
closed cycle (i.e. motion)
(separability implicit)

A-A Variables

$$\lambda = \lambda_0 \text{ const, closed loop}$$

$$I = \oint p dq \quad \begin{cases} \text{exact} \\ \text{COM} \end{cases}$$

E, I const.

$$\dot{I} = 0 \text{ is HEOM}$$

Variables on which
system is integrated
i.e. $\dot{I} = 0$

separable system \Rightarrow
1 action variable/
cycle.

Examples:

- H.O.: 1D
- 2D
- general 1D
- Free particle in box

1) 1D H.O.

$$H = \frac{1}{2} (p^2 + \omega^2 q^2)$$

$$\left(\frac{\partial S}{\partial q}\right)^2 + \omega^2 q^2 = E \quad \text{is H-J.}$$

$$I = \frac{1}{2\pi} \oint (E - \omega^2 \frac{q^2}{2})^{1/2} dq$$

$$\oint = 2 \int_{q_-}^{q_+}$$

$$E = \omega^2 q^2 \rightarrow \text{turning pts.}$$

$$q_{\pm} = \pm \sqrt{E}/\omega$$

, "

$$I = \frac{2}{2\pi} \int_{q_-}^{q_+} \left[(E - \omega^2 \frac{q^2}{2}) \right]^{1/2} dq$$

$$q = \sqrt{2E}/\omega \cos \theta, \quad dq = \sqrt{2E}/\omega \sin \theta$$

$$\underline{\infty}, \quad I = E/\omega$$

$$p = \underline{I} \equiv \text{"New" momentum}$$

$$H = E = \underline{I} \omega \quad \underline{\infty}, \quad \mathcal{O} = \frac{\partial H}{\partial \underline{I}} = \omega$$

$$\mathcal{O} = \omega t + \mathcal{O}_0$$

$$S = S(E, \underline{I}) = \int_{\underline{I}_0}^{\underline{I}} d\underline{I} \left(I\omega - \frac{\omega^2 I^2}{2} \right)^{1/2}$$

2) For 2D,

$$H = \frac{p_1^2}{2} + \frac{p_2^2}{2} + \frac{\omega^2 q_1^2}{2} + \frac{\omega^2 q_2^2}{2}$$

$$H = f(1) + f(2) = E \quad \text{separable!}$$

$$f(1) = \frac{p_1^2}{2} + \frac{\omega^2 q_1^2}{2} = E_1 \rightarrow \text{const.}$$

$$f(2) = \frac{p_2^2}{2} + \frac{\omega^2 q_2^2}{2} = E_2 \rightarrow \text{const.}$$

So, for action variables I_1, I_2 :

$$I_1 = \frac{1}{2\pi} \oint p_1 dq = \frac{1}{2\pi} \oint p_1(q_1) dq_1 = \frac{E_1}{\omega_1}$$

$$I_2 = E_2 / \omega_2$$

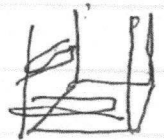
$$H(I_1, I_2) = E = E_1 + E_2 = I_1 \omega_1 + I_2 \omega_2$$

→ separable, so

→ additive form of H in A-A variables

2) Free Particle in 2D $\begin{cases} 0 < x < a \\ 0 < y < b \end{cases}$ (hard wall)

$$H = \frac{1}{2m} (p_x^2 + p_y^2)$$



→ 2 Degr Freedom ⇒ 2 I's, 2 ω's

$$\therefore I_1 = \frac{1}{2\pi} \oint p_x dx$$

$$I_2 = \frac{1}{2\pi} \oint p_y dy$$

$$\oint p_x dx = \int_a^a p_{x+} dx + \int a^0 p_{x-} dx$$

$$p_{x+} = -p_{x-} \quad (\text{reverse when bounce off wall})$$

$$\oint p_x dx = 2a |p_x|$$

$$\therefore I_1 = \frac{a}{\pi} |p_x|$$

$$I_2 = \frac{b}{\pi} |p_y|$$

$$\text{So } H = E = \frac{p_x^2 + p_y^2}{2m}$$

$$= \frac{\pi^2}{2m} \left(\frac{I_1^2}{a^2} + \frac{I_2^2}{b^2} \right)$$

$$\omega(I_1, I_2) = \frac{\partial E(I_1, I_2)}{\partial I_{1,2}} = \left(\frac{\pi^2}{m} \frac{I_1}{a^2}, \frac{\pi^2}{m} \frac{I_2}{b^2} \right)$$

2 points:

① contract:

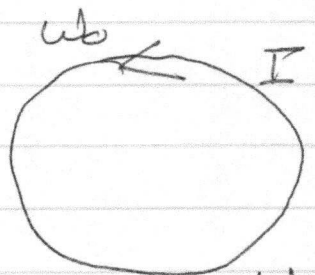
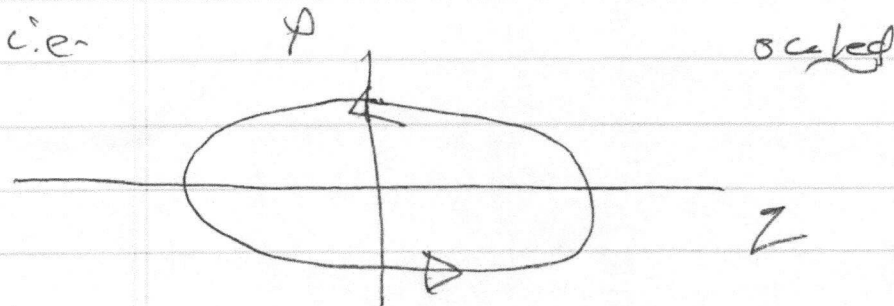
→ H.O.

$$\omega(I) = \omega_0 = \text{const.}$$

$$\frac{\partial \omega}{\partial I} = 0$$

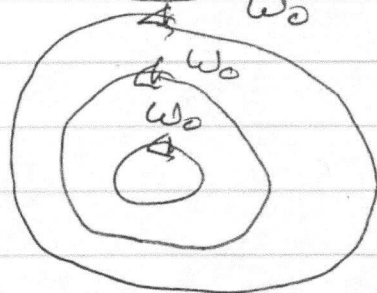
$I\omega_0 = E \rightarrow$ constant frequency

\rightarrow no shear in winding rate



and all I centers have same rotation frequency ω_0

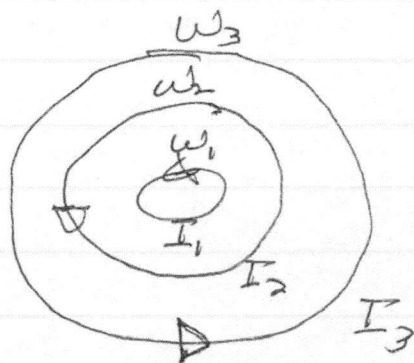
i.e.



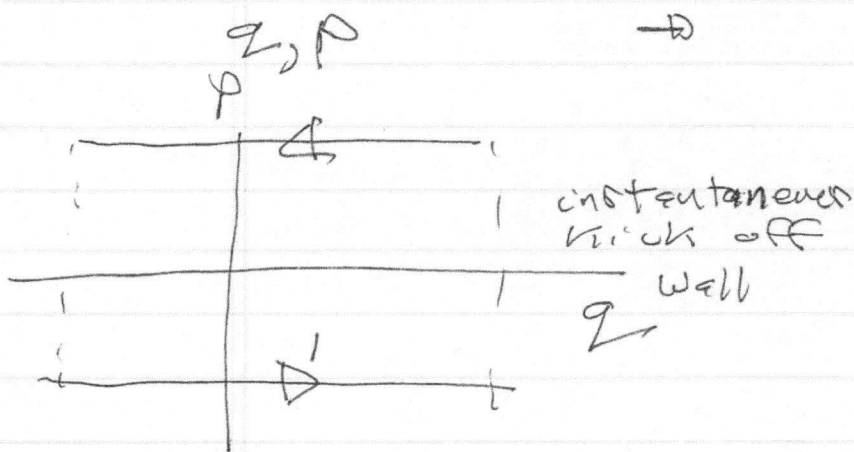
\Rightarrow box $\omega(I) = \frac{\pi^2 I}{m a^2}$

$\partial\omega(I)/\partial I \neq$ $\omega \sim |p|$
 \Rightarrow winding rate varies with I
 \Rightarrow "shear"

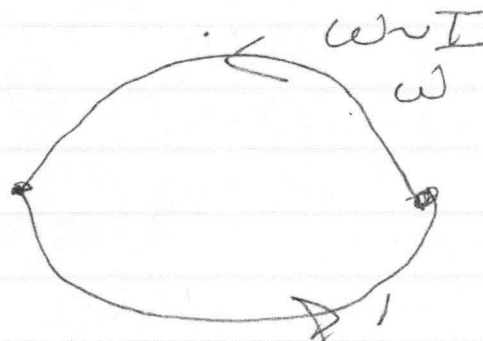
c.e



winding rate increases with I (i.e. $\omega \sim I$)
 \Rightarrow differential rotation



I, ω



c.e. top box - top circle, etc.

? H.O. is linear problem, with $\partial \omega / \partial I = 0$

Box has $\partial \omega / \partial I \neq 0$, yet is linear too?

Why?

n.b. Consider general 1D potential:

$$H = p^2 + V(x)$$

$$I = \oint \frac{p dx}{2\pi} = \frac{1}{2\pi} \oint [E - V(x)]^{1/2} dx = I(E)$$

$$\omega = \partial E(I) / \partial I$$

Now, for $V(x) \sim \beta x^4$

$$I \sim C' E^{3/4}$$

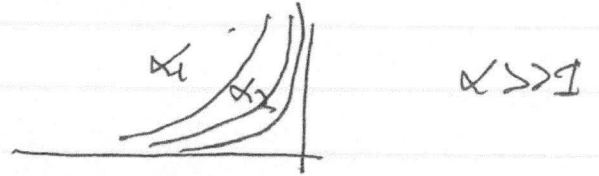
$$\Rightarrow E \sim C I^{4/3} \text{ so } \omega(I) \sim C'' I^{1/3}$$

shear!

⇒ Nonlinearity develops from $V \propto x^\alpha$ potential for $\alpha > 2$.

∴ View hard wall as a limiting case
i.e.

$$V = V_0 (x/a)^\alpha$$



so hard wall boundary condition appears as nonlinearity due high high powers implicit in piecewise continuous potential.

② Reln. QM

classically: $H = E = \frac{\pi^2}{2m} \left(\frac{I_1^2}{a^2} + \frac{I_2^2}{b^2} \right)$

if $\left. \begin{array}{l} I_1 \rightarrow n\hbar \\ I_2 \rightarrow m\hbar \end{array} \right\}$ quantize action variables

$$E = \frac{\pi^2 \hbar^2}{2m} \left(\frac{n^2}{a^2} + \frac{m^2}{b^2} \right) \rightarrow \text{eigenstates of free QM particle in box}$$

inside: Can observe correspondance

Classical

Quantum

$$I = E/\omega$$

$$E = (N + 1/2) \hbar \omega$$

$$H = I \omega$$

↓
quanta of occupation
(quantum #) Δ

∴ suggests view I as classical # of excitations/waves → exciton density

straight forward to generalize: (linear wave) ↑ wave energy density

$$I = E/\omega$$

$$N(\underline{k}, \omega) = \frac{E(\underline{k}, \omega)}{\hbar \omega}$$

↓
linear H.O.

↓
Action Density
as wave density, # waves

↓
wave frequency

→ General Properties of Motion in
s dimensions.

system

Now, consider:

- s degrees of freedom (arbitrary)
- separable H-J. equation

$$S = \sum_{i=1}^s S_i(E) \quad (\text{i.e. integrable})$$

∴ can define s action variables I_i

$$I_i = \oint \frac{p_i dq_i}{2\pi} \quad \text{i.e. } s\text{-IOMs.}$$

and $\theta_i = \partial S_0 / \partial I_i$ angle variables

so

$$\dot{I}_i = 0$$

$$\dot{\theta}_i = \omega_i(E) + t + t_0$$

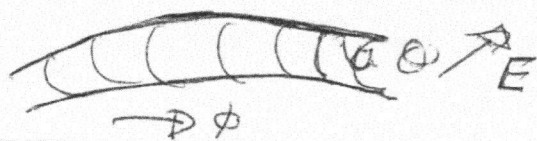
$$\omega_i(E) = \partial E / \partial I_i$$

i.e. for $s=2$

$$\dot{I}_1 = \dot{I}_2 = 0$$

$$\omega_1 = \partial E / \partial I_1$$

$$\theta_1 = \omega_1(E)t + t_0$$



change I
 \rightarrow change surf
 \rightarrow nested surfaces.

phase space is 2 torus. Fixed $E \Rightarrow$ motion on toroidal surface.
 [In general, phase space is S -torus.]

$$\begin{aligned} \theta &= \omega_1(E)t \\ \phi &= \omega_2(E)t \end{aligned}$$

$$\theta = \frac{\omega_1(E)}{\omega_2(E)} \phi$$

\rightarrow Now, for any $F(\underline{q}, \underline{p})$, can write:
Fourier series

$$F = \sum_{l_1} \sum_{l_2} \dots \sum_{l_s} A_{l_1, l_2, \dots, l_s} \exp \left[i(l_1 \theta_1 + l_2 \theta_2 + \dots + l_s \theta_s) \right]$$

l_1, l_2, \dots, l_s integers, \Rightarrow define vector \underline{l}

equivalently:

$$F = \sum_{l_1} \sum_{l_2} \dots \sum_{l_s} A_{l_1, l_2, \dots, l_s} \exp \left[i \omega_i t \left(\underline{l} \cdot \frac{\partial F}{\partial \underline{I}} \right) \right]$$

$$\underline{l} \cdot \frac{\partial F}{\partial \underline{I}} = l_1 \frac{\partial F}{\partial I_1} + l_2 \frac{\partial F}{\partial I_2} + \dots + l_s \frac{\partial F}{\partial I_s}$$

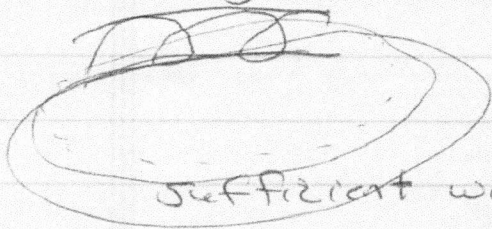
Now, in general:

→ frequencies not commensurate, so F
not periodic i.e. $\underline{I} \cdot \frac{\partial E}{\partial \underline{I}}$ irrational

→ indeed, system generally not periodic in any coordinate (except for special E).

but, for sufficient time,
come arbitrarily close,
to starting point.

system will
→ Poincaré
Recurrence
Thm. !



sufficient windings

i.e. trajectory, ergodic-
ally covers surface
of torus

∴ motion is "conditionally" periodic.

But; degeneracy happens!

- degeneracy: $n\omega_i = m\omega_j$

- all ω commensurate \Rightarrow complete degeneracy.

So, as in Kepler problem, \Rightarrow degeneracy
implies reduction in number of independent
 I_i . Why?

Commensurate frequencies \Rightarrow

$$n_1 \omega_1 = n_2 \omega_2$$

$$n_1 \frac{\partial E}{\partial I_1} = n_2 \frac{\partial E}{\partial I_2}$$

so $E = E(n_2 I_1 + n_1 I_2)$

i.e. - energy depends on sum of action variables

linear superposition

\Rightarrow

- degeneracy

\Rightarrow

- can make canonical transformation
so $E = E(I')$, only.

\Rightarrow

\therefore in degenerate motion, there is an increase in the number of one-valued integrals of the motion, relative to non-degenerate case.

i.e. non-degenerate motion - S degs freedom

$$2S-1 \rightarrow \text{IOM'S}$$

$\int S$ values $I_i \rightarrow$ single valued I_i

$\int S-1$ values of $Q_i \partial E / \partial I_k - Q_k \partial E / \partial I_i$

note: $S-1$ values \rightarrow phases (i.e.'s) of angle variables.

\rightarrow not single valued.

but if degeneracy, note though:

$\rightarrow n_1 \theta_1 - n_2 \theta_2$ not single valued

cf 15, to \rightarrow addition of 2π !

16
 $\rightarrow \sin(n_1 \theta_1 - n_2 \theta_2)$ is single valued,
 (etc)